

# ECON 730: Causal Inference with Panel Data

## Lecture 3: Panel Experiments and Dynamic Causal Effects

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## Motivation: Why Panel Experiments?

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# Why Study Panel Experiments?

- Last lecture: Potential outcomes depend on **treatment histories**, not just current treatment
- Today: What can we learn when treatments are **randomly assigned** over time?
- Panel experiments provide the **experimental foundation** for understanding:
  - ▶ How to define causal effects when past treatments affect current outcomes
  - ▶ Why standard estimators can fail
  - ▶ What identification looks like under randomization
- This builds intuition for the **observational methods** (DiD, etc.) we'll study later

**Main reference:** Bojinov, Rambachan and Shephard (2021) – “Panel Experiments and Dynamic Causal Effects: A Finite Population Perspective”

# The Carryover Problem

- In panel experiments, we randomly assign treatments over multiple periods
- **Key challenge:** Past treatments may affect current outcomes (*carryover effects*)
- **Examples:**
  - ▶ A/B testing at tech companies: User behavior today depends on past experiences
  - ▶ Clinical trials with repeated dosing: Drug effects accumulate over time
  - ▶ Pricing experiments: Past prices affect current demand through learning
- Standard cross-sectional methods assume  $Y_{it}(d)$  – i.e., the outcome depends only on *current* treatment
- But the truth may be  $Y_{it}(d_{i,1}, d_{i,2}, \dots, d_{i,T})$  – i.e., the outcome depends on the *entire history*

# Roadmap for Today

1. **Framework:** Potential outcomes indexed by treatment paths
2. **Estimands:** Lag- $p$  dynamic causal effects
3. **Identification & Estimation:** Sequential randomization + Horvitz-Thompson
4. **Special Cases:** RCT, Bernoulli, staggered adoption as illustrations
5. **Application:** Prisoners' dilemma experiment
6. **Why not Fixed Effects?** Bias under carryover + serial correlation
7. **Bridge:** From experiments to observational data

## Framework: Potential Outcomes with Treatment Paths

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## Setup: The Potential Outcome Panel

- **Units:**  $i \in \{1, \dots, N\}$  observed over **periods:**  $t \in \{1, \dots, T\}$
- **Treatment:**  $D_{it} \in \mathcal{D}$  assigned to unit  $i$  at time  $t$ 
  - ▶ For binary treatment:  $\mathcal{D} = \{0, 1\}$
- **Treatment path** for unit  $i$ : The sequence of all treatments up to time  $T$

$$\mathbf{d}_{i,1:T} = (d_{i,1}, d_{i,2}, \dots, d_{i,T}) \in \mathcal{D}^T$$

- **Cross-sectional assignment** at time  $t$ : All treatments at period  $t$

$$\mathbf{d}_{1:N,t} = (d_{1,t}, d_{2,t}, \dots, d_{N,t}) \in \mathcal{D}^N$$

# Potential Outcomes Depend on Treatment Paths

## Definition (Potential Outcome)

The **potential outcome** for unit  $i$  at time  $t$  along treatment path  $\mathbf{d}_{i,1:T} \in \mathcal{D}^T$  is:

$$Y_{it}(\mathbf{d}_{i,1:T})$$

- In principle,  $Y_{it}$  can depend on the **entire** treatment path
- This allows arbitrary spillovers **across time** within a unit
- We assume **no interference across units** (SUTVA):  $Y_{it}$  doesn't depend on  $\mathbf{d}_{j,1:T}$  for  $j \neq i$

# Key Assumption: Non-Anticipation

## Assumption (Non-Anticipating Potential Outcomes)

For all units  $i$ , periods  $t$ , and treatment paths  $\mathbf{d}_{i,1:T}, \tilde{\mathbf{d}}_{i,1:T} \in \mathcal{D}^T$ :

$$Y_{it}(\mathbf{d}_{i,1:T}) = Y_{it}(\tilde{\mathbf{d}}_{i,1:T}) \quad \text{whenever} \quad \mathbf{d}_{i,1:t} = \tilde{\mathbf{d}}_{i,1:t}$$

### Interpretation:

- Potential outcomes at time  $t$  only depend on treatments **up to time  $t$**
- Future treatments don't affect **current** outcomes
- But **past and current** treatments can have **arbitrary effects**

Under non-anticipation:  $Y_{it}(\mathbf{d}_{i,1:t})$  instead of  $Y_{it}(\mathbf{d}_{i,1:T})$

Q: What if treatment is announced in advance?

# Key Assumption: Non-Anticipation

## Assumption (Non-Anticipating Potential Outcomes)

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### Interpretation:

- Potential outcomes at time  $t$  only depend on treatments **up to time  $t$**
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Under non-anticipation:  $Y_{it}(\mathbf{d}_{i,1:t})$  instead of  $Y_{it}(\mathbf{d}_{i,1:T})$

**Q:** What if treatment is announced in advance? *A: Define the "treatment" as the announcement, not implementation. Non-anticipation then holds relative to the announcement date.*

# Connection to Lecture 2: Treatment Sequences

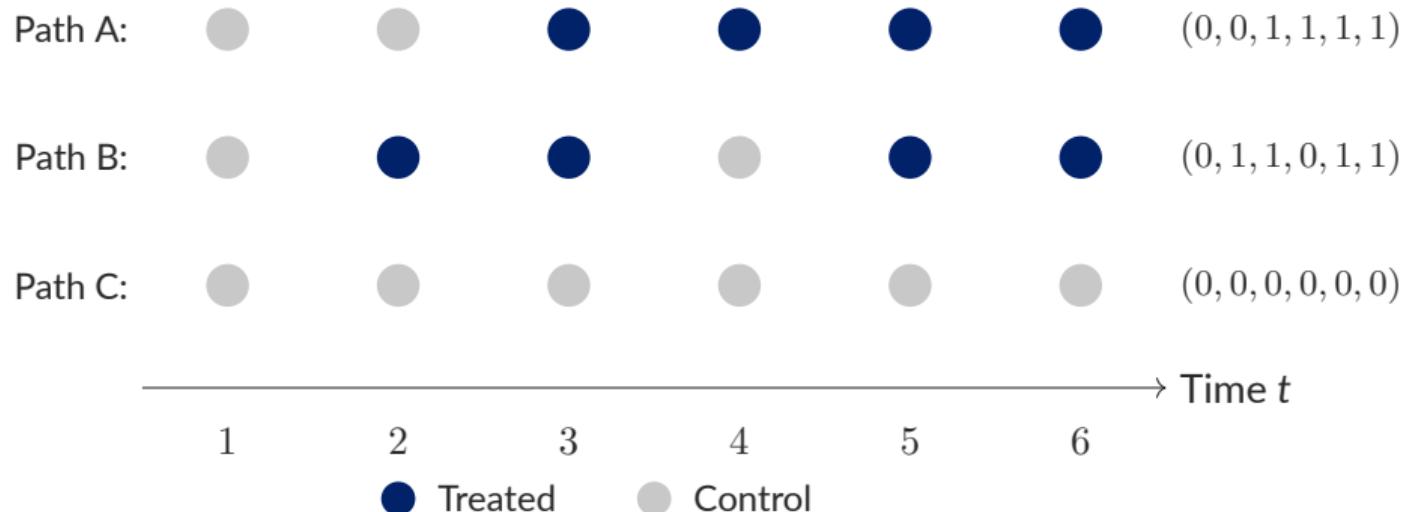
Lecture 2 introduced:  $Y_{it}(\mathbf{d}_{i,1:T})$  where  $\mathbf{d}_{i,1:T} = (d_{i,1}, \dots, d_{i,T})$  (Robins)

## What's new in this lecture?

- **Non-anticipation:** Restricts dependence to treatments *up to time t*
- **Tractable estimands:** Focusing on recent treatment history instead of the full path
- **How experiments help:** Known assignment probabilities  $\rightarrow$  design-based inference
- **When standard methods fail:** Why fixed effects can mislead under carryover

This lecture provides the *experimental foundation* for treatment path dependence. Later: DiD uses parallel trends instead of randomization.

# Treatment Path Visualization



**Key insight:** Different paths lead to different potential outcomes at  $t = 6$ :

$$Y_{i6}(\text{Path A}) \neq Y_{i6}(\text{Path B}) \neq Y_{i6}(\text{Path C})$$

## Estimands: Lag- $p$ Dynamic Causal Effects

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# Defining Dynamic Causal Effects

A **dynamic causal effect** compares potential outcomes along different treatment paths:

$$\tau_{it}(\mathbf{d}_{i,1:t}, \tilde{\mathbf{d}}_{i,1:t}) := Y_{it}(\mathbf{d}_{i,1:t}) - Y_{it}(\tilde{\mathbf{d}}_{i,1:t})$$

**Problem:** The number of comparisons grows exponentially with  $t$ . **Solution:** Lag- $p$  effects.

## Definition (Lag- $p$ Dynamic Causal Effect)

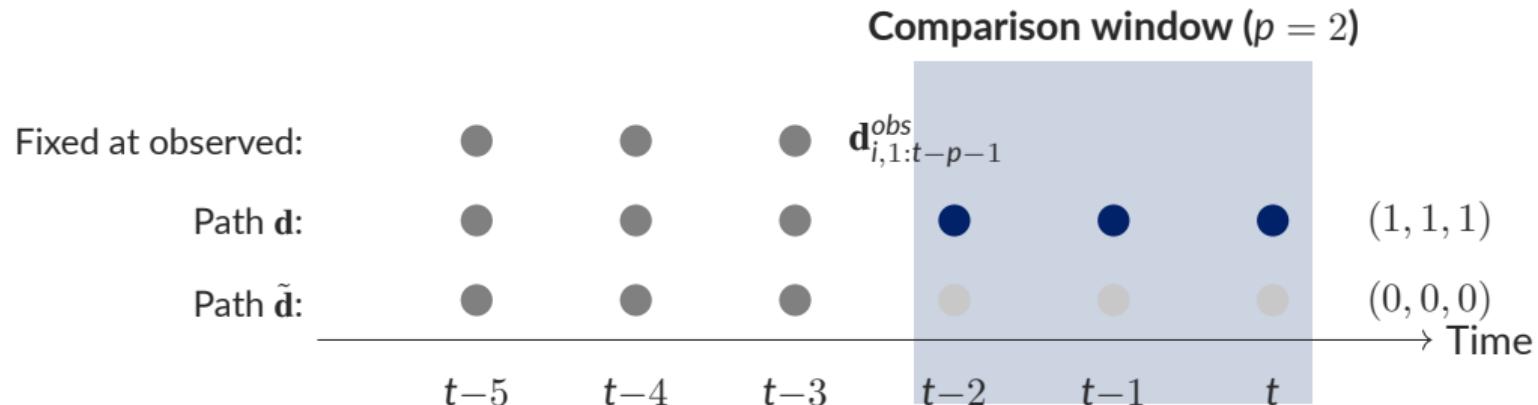
For  $0 \leq p < t$  and treatment sequences  $\mathbf{d}, \tilde{\mathbf{d}} \in \mathcal{D}^{p+1}$ :

$$\tau_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p) := Y_{it}(\mathbf{d}_{i,1:t-p-1}^{obs}, \mathbf{d}) - Y_{it}(\mathbf{d}_{i,1:t-p-1}^{obs}, \tilde{\mathbf{d}})$$

where  $\mathbf{d}_{i,1:t-p-1}^{obs}$  denotes unit  $i$ 's **realized** path up to period  $t-p-1$ .

Note:  $p < t$  ensures there are enough past periods. Choosing  $p$ : bias-variance tradeoff (larger  $p$  captures more carryover but needs more data).

# Interpreting Lag- $p$ Effects



Lag- $p$  effect with  $p = 2$ ,  $\mathbf{d} = (1, 1, 1)$ ,  $\tilde{\mathbf{d}} = (0, 0, 0)$ :

$$\tau_{it}((1, 1, 1), (0, 0, 0); 2) = Y_{it}(\mathbf{d}_{i,1:t-3}^{obs}, 1, 1, 1) - Y_{it}(\mathbf{d}_{i,1:t-3}^{obs}, 0, 0, 0)$$

Effect of treatment in periods  $t-2, t-1, t$  vs. control, conditional on the observed earlier path.

# Special Cases: Lag-0 and Contemporaneous Effects

Lag-0 dynamic causal effect ( $p = 0$ ):

$$\tau_{it}(d, \tilde{d}; 0) = Y_{it}(\mathbf{d}_{i,1:t-1}^{obs}, d) - Y_{it}(\mathbf{d}_{i,1:t-1}^{obs}, \tilde{d})$$

- Compares treatment  $d$  vs.  $\tilde{d}$  at time  $t$  only, holding the **entire past** fixed
- If **no carryover**: reduces to  $Y_{it}(1) - Y_{it}(0)$  (standard effect)

**Key:** The lag-0 effect is *conditional on history*. For the same unit,  $\tau_{it}(1, 0; 0)$  can differ depending on prior treatment status!

**Example:** Suppose the treatment is a pain medication.

- If unit  $i$  was treated yesterday: tolerance may develop  $\rightarrow$  *smaller*  $\tau_{it}(1, 0; 0)$
- If unit  $i$  was *not* treated recently: full drug effect  $\rightarrow$  *larger*  $\tau_{it}(1, 0; 0)$

# Average Lag- $p$ Dynamic Causal Effects

## Definition (Average Lag- $p$ Dynamic Causal Effects)

For  $p < T$  and  $\mathbf{d}, \tilde{\mathbf{d}} \in \mathcal{D}^{p+1}$ :

**Time- $t$  average** (across units):  $\bar{\tau}_{.t}(\mathbf{d}, \tilde{\mathbf{d}}; p) := \frac{1}{N} \sum_{i=1}^N \tau_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$

**Unit- $i$  average** (across time):  $\bar{\tau}_{i.}(\mathbf{d}, \tilde{\mathbf{d}}; p) := \frac{1}{T-p} \sum_{t=p+1}^T \tau_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$

**Total average** (across all  $i, t$ ):  $\bar{\tau}(\mathbf{d}, \tilde{\mathbf{d}}; p) := \frac{1}{N(T-p)} \sum_{i=1}^N \sum_{t=p+1}^T \tau_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$

Note: Sums start at  $t = p + 1$  because we need  $p$  prior periods. Compare to Lecture 2: ATE( $t$ ), unit-specific, overall ATE.

## Identification and Estimation

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# The Fundamental Problem of Causal Inference (Revisited)

Recall from Lecture 2: We cannot learn causal effects directly from data without structure.

The fundamental problem:

- For each unit  $i$  at time  $t$ , we observe **one** outcome along the realized path
- But potential outcomes exist for **every** possible treatment path  $\mathbf{d}_{i,1:t} \in \mathcal{D}^t$
- With binary treatment and  $T$  periods:  $2^T$  potential outcomes per unit, observe only 1

What structure can help?

- In observational settings: parallel trends, selection on observables, etc.
- In **experiments**: we know the assignment mechanism

**This lecture:** Exploit known assignment probabilities from randomization to construct unbiased estimators via inverse probability weighting.

# Assignment Mechanism: Sequential Randomization

What makes this a panel *experiment*? The assignment mechanism is known.

## Definition (Sequentially Randomized Assignments)

Assignments are **sequentially randomized** if for all  $t \in \{1, \dots, T\}$ :

$$\Pr(\mathbf{D}_{1:N,t} | \mathbf{D}_{1:N,1:t-1}, \mathbf{Y}_{1:N,1:T}) = \Pr(\mathbf{D}_{1:N,t} | \mathbf{D}_{1:N,1:t-1}, \mathbf{Y}_{1:N,1:t-1}(\mathbf{D}_{1:N,1:t-1}))$$

## Interpretation:

- Assignment at  $t$  can depend on **past assignments** and **past observed outcomes**
- But not on **future** potential outcomes or **counterfactual** past outcomes
- This is the panel analogue of “unconfounded” assignment
- In words: knowing which outcomes *would have been* realized under alternative paths provides no additional information about current assignment

**Important:** Since we’re in an *experiment*, assignment probabilities are **known** to the researcher.

# Individualistic Assignments

## Definition (Individualistic Assignment)

Assignments are **individualistic** for unit  $i$  if:

$$\Pr(D_{it} | D_{-i,t}, \mathcal{F}_{1:N,t-1,T}) = \Pr(D_{it} | \mathbf{D}_{i,1:t-1}, \mathbf{Y}_{i,1:t-1})$$

where  $\mathcal{F}_{1:N,t,T}$  is the filtration generated by treatments and potential outcomes.

### Interpretation:

- Unit  $i$ 's assignment depends only on its **own** past, not on other units
- Conditional on own history, assignments are **independent across units**

**Example:** Bernoulli assignment where  $\Pr(D_{it} = 1) = q$  for all  $i, t$  independently.

# The Adapted Propensity Score: Definition

## Definition (Adapted Propensity Score)

For unit  $i$  at time  $t$  and treatment sequence  $\mathbf{d} = (d_{t-p}, \dots, d_t) \in \mathcal{D}^{p+1}$ :

$$\pi_{i,t-p}(\mathbf{d}) := \Pr(\mathbf{D}_{i,t-p:t} = \mathbf{d} | \mathbf{D}_{i,1:t-p-1}, \mathbf{Y}_{i,1:t-1})$$

**What this measures:** Probability of observing path  $\mathbf{d}$  over periods  $t-p$  to  $t$ , conditional on the unit's past assignment and outcome history. (The subscript  $t-p$  denotes the *start* of the treatment window.)

## Why "adapted"?

- The propensity score can **change over time** as information accumulates
- But since the experiment is **designed**, we know these probabilities

## Assumption (Probabilistic Assignment (Overlap))

There exist constants  $0 < c_L < c_U < 1$  such that  $c_L < \pi_{i,t-p}(\mathbf{d}) < c_U$  for all  $i, t, \mathbf{d}$

# Computing the Adapted Propensity Score

**Step 1:** Identify the experimental design (Bernoulli, block, adaptive, etc.)

**Step 2:** Compute period-by-period probabilities. For path  $\mathbf{d} = (d_{t-p}, \dots, d_t)$ :

$$\pi_{i,t-p}(\mathbf{d}) = \prod_{s=t-p}^t \Pr(D_{is} = d_s \mid \text{history up to } s-1)$$

**Step 3:** Apply to specific designs

- **iid Bernoulli** with  $\Pr(D_{it} = 1) = q$ :  $\pi_{i,t-p}(\mathbf{d}) = q^{\#\{s: d_s=1\}} \cdot (1-q)^{\#\{s: d_s=0\}}$
- **Example:**  $p = 2$ ,  $q = 0.5$ ,  $\mathbf{d} = (1, 0, 1)$ :  $\pi_{i,t-2}(1, 0, 1) = (0.5)^2 \cdot (0.5)^1 = 0.125$

**Key insight:** We only need  $\pi_{i,t-p}(\mathbf{d})$  for the **observed** path – and we know it by design!

# Horvitz-Thompson Estimator: Building Block

## Definition $((i, t)$ -th Contribution to Lag- $p$ Effect Estimator)

For  $\mathbf{d}, \tilde{\mathbf{d}} \in \mathcal{D}^{p+1}$ :

$$\hat{\tau}_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p) = \frac{Y_{it} \cdot \mathbf{1}\{\mathbf{D}_{i,t-p:t} = \mathbf{d}\}}{\pi_{i,t-p}(\mathbf{d})} - \frac{Y_{it} \cdot \mathbf{1}\{\mathbf{D}_{i,t-p:t} = \tilde{\mathbf{d}}\}}{\pi_{i,t-p}(\tilde{\mathbf{d}})}$$

## Intuition:

- When unit  $i$  follows path  $\mathbf{d}$ : contribute  $Y_{it}/\pi_{i,t-p}(\mathbf{d})$
- When unit  $i$  follows path  $\tilde{\mathbf{d}}$ : contribute  $-Y_{it}/\pi_{i,t-p}(\tilde{\mathbf{d}})$
- Otherwise: contribute zero. IPW corrects for different path probabilities

This is an **estimation building block**. We aggregate these  $(i, t)$  contributions into **plug-in averages** to estimate population-level effects.

# Plug-in Average Estimators

## Definition (Plug-in Average Estimators)

**Time- $t$  average:**  $\hat{\tau}_{\cdot t}(\mathbf{d}, \tilde{\mathbf{d}}; p) := \frac{1}{N} \sum_{i=1}^N \hat{\tau}_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$

**Unit- $i$  average:**  $\hat{\tau}_{i \cdot}(\mathbf{d}, \tilde{\mathbf{d}}; p) := \frac{1}{T-p} \sum_{t=p+1}^T \hat{\tau}_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$

**Total average:**  $\hat{\tau}(\mathbf{d}, \tilde{\mathbf{d}}; p) := \frac{1}{N(T-p)} \sum_{i=1}^N \sum_{t=p+1}^T \hat{\tau}_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$

These estimate  $\bar{\tau}_{\cdot t}$ ,  $\bar{\tau}_{i \cdot}$ , and  $\bar{\tau}$  from earlier – **unbiased under randomization**.

# Key Result: Unbiasedness

**Theorem (Bojinov et al. (2021), Theorem 3.1)**

Under individualistic and probabilistic assignment:

$$\mathbb{E}[\hat{\tau}_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p) | \mathcal{F}_{i,t-p-1}] = \tau_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p)$$

The estimation error is a **martingale difference sequence** through time and **conditionally independent** across units.

**Implications:**

- The estimator is **unbiased** for the true lag- $p$  dynamic causal effect
- Unbiasedness is over the **randomization distribution** (design-based)
- No assumptions on the outcome model needed!

**Variance:** Can be **conservatively estimated** from the data. Plug-in averages are also unbiased.

# What Does Design-Based Unbiasedness Mean?

**Setup:**  $N = 4$ , binary treatment, Bernoulli(0.5), at period  $t$  ( $\mathcal{F}_{i,t-p-1}$  realized).  $2^4 = 16$  possible assignments.

$D_{1t}$	$D_{2t}$	$D_{3t}$	$D_{4t}$	$\hat{\tau}_{\cdot t}$
0	0	0	1	some number
		$\vdots$		$\vdots$
1	1	1	0	some number

“Unbiased” = average of  $\hat{\tau}_{\cdot t}$  over all 16 assignments equals  $\bar{\tau}_{\cdot t}$ .

**Design-based  $\neq$  model-based.** Potential outcomes are *fixed*; only assignments are random. We average over the *randomization distribution*, not over hypothetical repeated samples.

**Full panel:** Total randomization space is  $2^{NT}$ , but unbiasedness works **period by period** (Theorem 3.1 conditions on  $\mathcal{F}_{i,t-p-1}$ ), then aggregates via iterated expectations.

# Inference: Finite Population CLTs

**Theorem (Bojinov et al. (2021), Theorem 3.2)**

Under individualistic, probabilistic assignment with bounded potential outcomes:

**Time- $t$  specific CLT** (as  $N \rightarrow \infty$ ):

$$\frac{\sqrt{N}\{\hat{\tau}_{\cdot t}(\mathbf{d}, \tilde{\mathbf{d}}; p) - \bar{\tau}_{\cdot t}(\mathbf{d}, \tilde{\mathbf{d}}; p)\}}{\sigma_{\cdot t}} \xrightarrow{d} N(0, 1)$$

**Unit- $i$  specific CLT** (as  $T \rightarrow \infty$ ):

$$\frac{\sqrt{T-p}\{\hat{\tau}_{i \cdot}(\mathbf{d}, \tilde{\mathbf{d}}; p) - \bar{\tau}_{i \cdot}(\mathbf{d}, \tilde{\mathbf{d}}; p)\}}{\sigma_{i \cdot}} \xrightarrow{d} N(0, 1)$$

**Total average CLT** (as  $NT \rightarrow \infty$ ):

$$\frac{\sqrt{N(T-p)}\{\hat{\tau}(\mathbf{d}, \tilde{\mathbf{d}}; p) - \bar{\tau}(\mathbf{d}, \tilde{\mathbf{d}}; p)\}}{\sigma} \xrightarrow{d} N(0, 1)$$

# Inference: Key Points

## Key implications:

- **Time-specific inference** ( $N \rightarrow \infty$ ): Test effects at a given period across units
- **Unit-specific inference** ( $T \rightarrow \infty$ ): Test effects for a given unit across time
- **Total average inference** ( $NT \rightarrow \infty$ ): Pool across both dimensions

## Practical considerations:

- Variance can be **conservatively estimated** from the data
- Enables valid confidence intervals and hypothesis tests

## Two testing approaches:

1. *Conservative tests*: CLT + variance upper bound  $\rightarrow$  tests **weak null**  $H_0 : \bar{\tau} = 0$  (average effect is zero)
2. *Randomization tests*: Exact tests under **sharp null**  $\tau_{it} = 0$  for all  $(i, t)$  (no unit has any effect)

# Randomization Tests: The Idea

Under the **sharp null**  $H_0 : \tau_{it}(\mathbf{d}, \tilde{\mathbf{d}}; p) = 0$  for all  $(i, t)$ :

1. We can **impute all missing potential outcomes**: if no unit has any effect, then  $Y_{it}(\mathbf{d}) = Y_{it}(\tilde{\mathbf{d}})$  for all paths  $\rightarrow$  observed outcome = counterfactual outcome
2. Compute the HT test statistic for **every possible assignment**, not just the one that occurred
3. **p-value** = fraction of possible assignments producing a test statistic as extreme as the one observed

## Advantages:

- **Exact**: No asymptotic approximation needed – valid in finite samples
- Follows directly from Fisher's classical randomization inference

**Limitation:** The sharp null ( $\tau_{it} = 0$  for every unit at every time) is stronger than the weak null ( $\bar{\tau} = 0$ , the *average* is zero). The CLT-based conservative test handles the weak null.

## Identification and Estimation

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### Illustrative Special Cases

## Special Case 1: Single Treatment Date (RCT)

**Setup:**  $N$  units,  $T = 3$  periods. Period  $t=1$  is pre-treatment. Treatment randomized at  $t=2$  only:  $\Pr(D_{i2} = 1) = q$ . No treatment at  $t=1$  or  $t=3$ .

All units share the same pre-treatment path, so  $\mathbf{d}_{i,1}^{obs} = 0$  for everyone.

- **Lag-0 effect at  $t = 2$ :**  $\tau_{i2}(1, 0; 0) = Y_{i2}(0, 1) - Y_{i2}(0, 0)$  ⇒ Standard ATE
- **Lag-1 effect at  $t = 3$ :**  $\tau_{i3}(1, 0; 1) = Y_{i3}(0, 1, 0) - Y_{i3}(0, 0, 0)$  ⇒ Carryover effect

**Adapted propensity score:**  $\pi_{i,2}(1) = q$ ,  $\pi_{i,2}(0) = 1 - q$  – known by design.

**Absorbing variant:** If once treated, always treated: paths become  $(0, 0, 0)$  and  $(0, 1, 1)$ . Then lag-1 at  $t=3$  is  $Y_{i3}(0, 1, 1) - Y_{i3}(0, 0, 0)$  – conflating contemporaneous and carryover. This is the staggered adoption challenge.

**Key insight:** Even in a simple RCT with follow-up, a naïve “treatment effect” conflates contemporaneous and lagged effects. The lag- $p$  framework separates them cleanly.

## Special Case 2: iid Bernoulli Assignment

**Setup:** Each unit independently assigned  $D_{it} = 1$  with probability  $q$  at every period.

- **Treatment paths:** All  $2^T$  paths are possible, each with known probability
- **Adapted propensity score** for path  $\mathbf{d} = (d_{t-p}, \dots, d_t) \in \mathcal{D}^{p+1}$ :

$$\pi_{i,t-p}(\mathbf{d}) = q^k \cdot (1 - q)^{p+1-k}, \quad k = \#\{s : d_s = 1\}$$

- Same for all units and all time periods – no dependence on history
- **HT estimator:** IPW corrects for different path probabilities; naïve mean comparison would not

**Notable feature:** **No serial correlation** in treatment – successive treatments are independent:  $\text{Cov}(D_{it}, D_{is}) = 0$  for  $s \neq t$ . We will see why this independence property matters when we discuss fixed effects estimators.

## Special Case 3: Staggered Adoption

**Setup:** Treatment is **absorbing** – once treated, always treated. Units adopt at different times  $g \in \{1, \dots, T\}$ .

- **Treatment paths collapse to:**  $(0, \dots, 0, 1, \dots, 1)$  with switch point  $g$
- **Lag- $p$  effect** for unit treated at  $g$ , evaluated at  $t \geq g + p$  (unit must have been treated for at least  $p+1$  consecutive periods):  
Compares “treated for  $p+1$  consecutive periods” vs. “not yet treated”
- **Connection to Lecture 2:** Closely related to  $ATT(g, t)$  – the group-time treatment effect
- **Adapted propensity score:**  $\Pr(\text{adopt at } g \mid \text{not yet adopted by } g-1)$  – the *hazard* of adoption

**Notable feature:** Treatment is **perfectly serially correlated** once adopted – if  $D_{it} = 1$ , then  $D_{is} = 1$  for all  $s > t$ . Contrast with iid Bernoulli above!

We'll see why this serial correlation structure matters for FE estimators.

# HT Estimator: A Worked Example

**Setup:**  $N = 4$  units, period  $t = 2$ , Bernoulli(0.5), lag-0 effect  $\hat{\tau}_{.2}(1, 0; 0)$ .

Unit $i$	$D_{i2}$	$Y_{i2}$	HT contribution: $\frac{Y_{i2} \cdot \mathbf{1}\{D_{i2}=1\}}{\pi_{i2}(1)} - \frac{Y_{i2} \cdot \mathbf{1}\{D_{i2}=0\}}{\pi_{i2}(0)}$
1	1	8	$8/0.5 = 16$
2	0	3	$-3/0.5 = -6$
3	1	6	$6/0.5 = 12$
4	0	2	$-2/0.5 = -4$

$$\hat{\tau}_{.2} = \frac{1}{4}(16 - 6 + 12 - 4) = 4.5$$

**Check:** With equal propensity scores ( $\pi_{i2}(1) = 0.5$  for all  $i$ ), HT = difference in means:  
 $\bar{Y}_{\text{treated}} - \bar{Y}_{\text{control}} = 7 - 2.5 = 4.5 \checkmark$

What if propensity scores are **unequal**? Does simple mean comparison still work?

# Why IPW Matters: Unequal Propensity Scores

Same units, but now an **adaptive design**: propensity scores vary across units.

Unit $i$	$D_{i2}$	$Y_{i2}$	$\pi_{i2}(D_{i2})$	HT contribution
1	1	8	0.8	$8/0.8 = 10$
2	0	3	0.7	$-3/0.7 = -4.29$
3	1	6	0.3	$6/0.3 = 20$
4	0	2	0.4	$-2/0.4 = -5$

$$\hat{\tau}_{.2}^{HT} = \frac{1}{4}(10 - 4.29 + 20 - 5) = 5.18$$

Naïve difference in means:  $\bar{Y}_{\text{treated}} - \bar{Y}_{\text{control}} = 7 - 2.5 = 4.5 \neq 5.18$

**Why the difference?** Unit 3 ( $D_{i2} = 1, \pi = 0.3$ ) was *unlikely* to be treated — its outcome is more “informative” about treatment effects and gets **upweighted**. Naïve means ignore this, producing bias.

## Application: Prisoners' Dilemma Experiment

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# Application: Rational Cooperation in Games

**Setting:** Andreoni and Samuelson (2006) study cooperative behavior in a twice-repeated prisoners' dilemma.

**Design:**  $N = 110$  participants,  $T = 20$  rounds, randomly matched into pairs each round. **Outcome:** cooperation in period 1 of the game.

**Treatment** ( $D_{it} \in \{0, 1\}$ ): The payoff structure parameter  $\lambda$  is **randomly varied** each round.

- $D_{it} = 1$  (high  $\lambda$ ): Payoffs reward *patience* – cooperation is rational
- $D_{it} = 0$  (low  $\lambda$ ): Payoffs reward *immediacy* – defection is tempting

Treatment is randomly assigned each round  $\Rightarrow$  **Bernoulli-like** design. But past game structures may affect current behavior through **learning** – exactly the carryover concern.

# Results: Dynamic Causal Effects in the Experiment

	Lag- $p$			
	$p = 0$	$p = 1$	$p = 2$	$p = 3$
Point estimate $\hat{\tau}^\dagger(1, 0; p)$	0.285	0.058	0.134	0.089
Conservative $p$ -value	0.000	0.226	0.013	0.126
Randomization $p$ -value	0.000	0.263	0.012	0.114

†: Overall average HT estimator  $\hat{\tau}$  as defined earlier, pooling across all units and rounds. Conservative tests use CLT; randomization tests simulate under sharp null.

## Findings:

- **Strong contemporaneous effect ( $p = 0$ ):** Treatment increases cooperation by 28.5 pp
- **Suggestive lag-2 effects ( $p = 2$ ):** Past structures affect behavior ( $p$ -value = 0.012)

**Interpretation:** The lag-2 effect suggests *learning dynamics* – players update beliefs based on past experiences. This carryover would bias naïve FE regressions.

## Why Not Fixed Effects?

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# A Natural Question

We've established that Horvitz-Thompson estimators are unbiased.

But practitioners often use simpler **fixed effects** estimators.

**Do they work under carryover effects?**

**Spoiler:** In general, **no**. FE estimators can be substantially biased when there are carryover effects and serial correlation in treatment assignment.

# The Appeal of Fixed Effects

**Common practice:** Run OLS with unit fixed effects:

$$Y_{it} = \alpha_i + \beta D_{it} + \epsilon_{it}$$

**Why it seems reasonable:**

- Controls for time-invariant unit heterogeneity ( $\alpha_i$ )
- $\hat{\beta}$  should capture the “treatment effect”
- Simple, widely available in standard software

**Question:** Does the unit FE estimator  $\hat{\beta}_{UFE}$  recover a meaningful causal effect when there are **carryover effects**?

**Answer:** In general, **no** – and the bias can be substantial.

# Linear Potential Outcome Panel Model

Definition (Bojinov et al. (2021), Definition 7)

A linear potential outcome panel satisfies:

$$Y_{it}(d_{i,1:t}) = \beta_{it,0}d_{it} + \beta_{it,1}d_{i,t-1} + \cdots + \beta_{it,t-1}d_{i,1} + \epsilon_{it}$$

Interpretation:

- $\beta_{it,0}$ : **Contemporaneous effect** – effect of current treatment on current outcome
- $\beta_{it,s}$  for  $s > 0$ : **Carryover effect** – effect of treatment  $s$  periods ago
- $\epsilon_{it} = Y_{it}(\mathbf{0})$ : Potential outcome under never-treated path

This is a **structural model** for potential outcomes that separates contemporaneous from carry-over effects. It nests the no-carryover case ( $\beta_{it,s} = 0$  for  $s > 0$ ).

# The Unit Fixed Effects (UFE) Estimator

**Definition:** The unit fixed effects (UFE) estimator is:

$$\hat{\beta}_{UFE} = \frac{\sum_{i=1}^N \sum_{t=1}^T \tilde{Y}_{it} \tilde{D}_{it}}{\sum_{i=1}^N \sum_{t=1}^T \tilde{D}_{it}^2}$$

where  $\tilde{A}_{it} = A_{it} - \bar{A}_{i\cdot}$  denotes the **within-unit deviation** from unit  $i$ 's time average.

**Equivalently:** OLS coefficient from regressing  $Y_{it}$  on  $D_{it}$  with unit fixed effects:

$$Y_{it} = \alpha_i + \beta D_{it} + \text{error}_{it}$$

UFE uses **within-unit variation** in treatment over time to identify effects. It removes time-invariant unit heterogeneity.

# Bias of the Unit Fixed Effects Estimator

## Proposition (Bojinov et al. (2021), Proposition 4.1)

Under a linear potential outcome panel, as  $N \rightarrow \infty$ :

$$\hat{\beta}_{UFE} \xrightarrow{p} \underbrace{\frac{\sum_{t=1}^T \tilde{\kappa}_{D,\beta,t,t}}{\sum_{t=1}^T \tilde{\sigma}_{D,t}^2}}_{\text{Target}} + \underbrace{\frac{\sum_{t=1}^T \sum_{s=1}^{t-1} \tilde{\kappa}_{D,\beta,t,s}}{\sum_{t=1}^T \tilde{\sigma}_{D,t}^2}}_{\text{Carryover Bias}} + \underbrace{\frac{\sum_{t=1}^T \tilde{\delta}_t}{\sum_{t=1}^T \tilde{\sigma}_{D,t}^2}}_{\text{Specification Error}}$$

(Each quantity defined on the next slide.)

Three components:

1. **Target:** A variance-weighted average of contemporaneous effects  $\beta_{it,0}$
2. **Carryover bias:** Arises when past treatment affects outcomes *and* treatment is serially correlated
3. **Specification error:** Arises if untreated potential outcomes  $Y_{it}(\mathbf{0})$  vary over time

UFE is unbiased only when *both* carryover bias and specification error are zero.

# Unpacking Proposition 4.1: The Key Quantities

**Within-unit deviation:**  $\tilde{D}_{it} = D_{it} - \bar{D}_{i\cdot}$ , where  $\bar{D}_{i\cdot} = T^{-1} \sum_{t=1}^T D_{it}$

**Treatment variation:**  $\tilde{\sigma}_{D,t}^2 = \lim_{N \rightarrow \infty} N^{-1} \sum_i \text{Var}(\tilde{D}_{it})$

*How much within-unit treatment variation exists at time  $t$ ?*

**Effect-correlation interaction:**  $\tilde{\kappa}_{D,\beta,t,s} = \lim_{N \rightarrow \infty} N^{-1} \sum_i \beta_{it,s} \cdot \text{Cov}(\tilde{D}_{it}, \tilde{D}_{is})$

*How much does carryover from period  $s$  “leak” into the period- $t$  estimate?*

**Specification error:**  $\tilde{\delta}_t$  captures time-varying untreated outcomes

*Vanishes if  $Y_{it}(\mathbf{0})$  is time-invariant (conditional on unit FE)*

**The critical insight:** Carryover bias =  $\sum_{s < t} \beta_{it,s} \cdot \text{Cov}(\tilde{D}_{it}, \tilde{D}_{is})$ . This is the product of **carryover effects** and **serial correlation in treatment**. If either is zero, the bias vanishes.

# Discussion: What Target Parameter?

Even **without** carryover or specification error, UFE estimates:

$$\frac{\sum_{t=1}^T \tilde{\kappa}_{D,\beta,t,t}}{\sum_{t=1}^T \tilde{\sigma}_{D,t}^2} = \frac{\sum_t \left( N^{-1} \sum_i \beta_{it,0} \cdot \text{Var}(\tilde{D}_{it}) \right)}{\sum_t \left( N^{-1} \sum_i \text{Var}(\tilde{D}_{it}) \right)}$$

→ **Weights**  $\propto \text{Var}(\tilde{D}_{it})$ : Units/periods with more treatment variation get more weight.

**Key questions:**

- Are these weights **policy-relevant**? Do we care more about  $(i, t)$  with high treatment variation?
- What if effects are **heterogeneous** ( $\beta_{it,0}$  varies)? Weighted average  $\neq$  simple avg.
- How does this compare to **equally-weighted** averages from Horvitz-Thompson?

**Takeaway:** Unbiasedness requires specifying the *target*. UFE is unbiased for a *particular* weighted average – but weights come from *design*, not policy.

# When Does UFE Bias Matter?

Carryover bias  $\propto$  (carryover effects)  $\times$  (serial correlation in treatment)

		Serial Correlation in $D_{it}$	
		No (iid Bernoulli)	Yes (staggered)
No Carryover ( $\beta_{it,s} = 0$ for $s > 0$ )	Unbiased	Unbiased	
	Unbiased	BIASED	

**Surprising:** Under iid Bernoulli, UFE is unbiased even with carryover! Why?  $\text{Cov}(\tilde{D}_{it}, \tilde{D}_{is}) = 0$  for  $s \neq t$ , so the carryover bias term vanishes.

**Why staggered = guaranteed bias:** Under staggered adoption,  $D_{it} = 1$  for all  $t \geq g_i \Rightarrow \text{Cov}(\tilde{D}_{it}, \tilde{D}_{is}) > 0$  for post-adoption periods. Any  $\beta_{it,s} \neq 0$  makes the bias non-zero.

# Two-Way Fixed Effects: Same Issue

TWFE:  $Y_{it} = \alpha_i + \lambda_t + \beta D_{it} + \text{error}_{it}$

## Proposition (Bojinov et al. (2021), Proposition 4.2)

TWFE has the **same three-component bias structure** as UFE, with different weights.

Important distinction from DiD literature:

- **Staggered DiD issues** (Goodman-Bacon, 2021; Sun and Abraham, 2021; Borusyak, Jaravel and Spiess, 2024; Imai and Kim, 2021): arise even *without* carryover, under PT assumptions
- **Here:** bias arises specifically *because of* carryover effects

*Athey and Imbens (2021) also take a design-based approach to staggered adoption, but don't focus on carryover effects.*

**Takeaway:** When carryover effects are possible, use Horvitz-Thompson estimators – not unit FE or TWFE.

## From Experiments to Observational Data

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# From Experiments to Observational Data

So far: Propensity scores known by design  $\Rightarrow$  Horvitz-Thompson is unbiased.

What if we don't run the experiment? [Blackwell and Glynn \(2018\)](#) address this using the *same* framework:

- Same potential outcomes indexed by treatment histories:  $Y_{it}(\mathbf{d}_{i,1:t})$
- Same estimands: Contemporaneous effect  $\leftrightarrow$  lag-0; Lagged effects  $\leftrightarrow$  lag- $p$
- **Key difference:** Identification via *sequential ignorability* (selection on observables) – propensity scores must be **estimated**, not known

**Blackwell and Glynn's key insight:** With time-varying covariates affected by past treatment, standard regression cannot consistently estimate lagged effects (*post-treatment bias*). Solutions exist (inverse probability weighting, structural models) – see [Blackwell and Glynn \(2018\)](#) for details.

**Limitation:** Sequential ignorability *cannot* handle time-constant unmeasured confounders  $\Rightarrow$  motivates **DiD** and parallel trends.

## Key Takeaways

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# Key Takeaways

## What's unique to this lecture:

1. **Lag- $p$  effects:** Tractable treatment path comparisons nesting familiar settings
2. **Design-based identification:** Known propensity scores → unbiased HT estimation
3. **Finite population CLTs:** Valid inference without outcome model assumptions
4. **FE bias:** Bias  $\propto$  (carryover)  $\times$  (serial correlation) — guaranteed under staggered adoption
5. **Roadmap:** Experiments → selection on observables (Blackwell and Glynn, 2018) → DiD (parallel trends)

**Main message:** When carryover effects are possible, don't default to TWFE. DiD provides an alternative that handles unmeasured time-constant confounders.

**Next lecture:** Efficient Estimation with Staggered Designs.

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